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numerous multinational cases globally, focusing on mergers and acquisitions, private equity transactions, foreign direct investments and corporate governance matters.

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Textbook reference for lectures 1-13 is . Applied Nonlinear Control, Slotine and Li, Prentice-Hall 1991. Main references for lectures 14-20 are . R1 Lohmiller, W., and Slotine, J.J.E., "On Contraction Analysis for Nonlinear Systems," Automatica, 34(6), 1998 R2 Slotine, J.J.E., "Modular Stability Tools

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for Distributed Computation and Control," Int. J. Adaptive Control and Signal Processing, 17(6 ...

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Slotine, J.-J. E. (Jean-Jacques E.)
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Jacques E. Slotine, Weiping Li p. cm.

Includes bibliographical references.

ISBN 0-13-040890-5 1, Nonlinear control theory. I. Li, Weiping. II. Title.

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Isabelle Slotine currently lives in Boston, MA; in the past Isabelle has also lived in Cambridge MA. We know

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that Isabelle is single at this point. Jean-jacques Slotine, Jean Slotine, Evelyne Smithers, Michael Civile and Amy Hernandez, and many others are family members and associates of Isabelle. [Read Full Summary](#)

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~~Background Report at ...~~

Summary: Jean Slotine is 61 years old today because Jean's birthday is on 10/01/1959. Previous to Jean's current city of Boston, MA, Jean Slotine lived in Woods Hole MA and Cambridge MA. In the past, Jean has also been known as Jean Jacques E Slotine,

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Jean-jacques E Slotine, Jean Jacques Slotine and Jean J Slotine.

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People The Nonlinear Systems Laboratory is headed by Professor Jean-Jacques Slotine. Members and

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Professor Slotine is the Director of the Nonlinear Systems Laboratory which

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studies general mathematical principles of nonlinear system stability, adaptation, and learning, and how they apply to robots and to models of biological control.

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Professor of Mechanical Engineering and Information Sciences, Professor of Brain and Cognitive Sciences, and Director of the Nonlinear Systems Laboratory. He received his Ph.D. from the Massachusetts Institute of Technology in 1983, at age 23.

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~~JEAN-JACQUES SLOTINE~~

Jean-Jacques Slotine was born in Paris in 1959. He received his Ph.D. from the Massachusetts Institute of Technology (MIT), Cambridge, MA, USA, in 1983. After working at Bell Labs in the computer research department, in 1984 he joined the faculty at MIT, where he is

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Proceedings of the Fifth Yale
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~~Control—Günter ...~~

Asada, H., and J. J. Slotine. Robot Analysis and Control. New York, NY: Wiley, 1986. ISBN: 9780471830290.

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practice or advanced research topics. Includes carefully devised conceptual diagrams, discussion of current research topics with references to the latest publications, and end-of-book problem sets. Appendixes. Bibliography.

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This book contains the text of the plenary lectures and the mini-courses of the European Control Conference (ECC'93) held in Groningen, the Netherlands, June 25-July 1, 1993. However, the book is not your usual conference proceedings. Instead, the authors took this occasion to take a

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broad overview of the field of control and discuss its development both from a theoretical as well as from an engineering perspective. The first essay is by the key-note speaker of the conference, A.G.J. Mac Farlane. It consists of a non-technical discussion of information processing and

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knowledge acquisition as the key features of control engineering technology. The next six articles are accounts of the plenary addresses. The contribution by R.W. Brockett concerns a mathematical framework for modelling motion control, a central question in robotics and vision. In the

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paper by M. Morari the engineering and the economic relevance of chemical process control are considered, in particular statistical quality control and the control of systems with constraints. The article by A.C.P.M. Backx is written from an industrial perspective. The author is

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director of an engineering consulting firm involved in the design of industrial control equipment. Specifically, the possibility of obtaining high performance and reliable controllers by modelling, identification, and optimizing industrial processes is discussed.

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This volume represents most aspects of the rich and growing field of nonlinear control. These proceedings contain 78 papers, including six plenary lectures, striking a balance between theory and applications. Subjects covered include feedback

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stabilization, nonlinear and adaptive control of electromechanical systems, nonholonomic systems. Generalized state space systems, algebraic computing in nonlinear systems theory, decoupling, linearization and model-matching and robust control are also covered.

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This book gathers the outcomes of the thirteenth Workshop on the Algorithmic Foundations of Robotics (WAFR), the premier event for showcasing cutting-edge research on algorithmic robotics. The latest WAFR, held at Universidad Politécnica de Yucatán in Mérida,

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México on December 9–11, 2018, continued this tradition. This book contains fifty-four papers presented at WAFR, which highlight the latest research on fundamental algorithmic robotics (e.g., planning, learning, navigation, control, manipulation, optimality, completeness, and

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complexity) demonstrated through several applications involving multi-robot systems, perception, and contact manipulation. Addressing a diverse range of topics in papers prepared by expert contributors, the book reflects the state of the art and outlines future directions in the field of algorithmic

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Hardware/software control architectures; Industrial robot-control algorithms. Furthermore, established research results involving description of end-effector orientation, closed kinematic chains, kinematic redundancy and singularities, dynamic parameter identification, robust and

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adaptive control and force/motion control are provided. To provide readers with a homogeneous background, three appendices are included on: Linear algebra; Rigid-body mechanics; Feedback control. To acquire practical skill, more than 50 examples and case studies are

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carefully worked out and interwoven through the text, with frequent resort to simulation. In addition, more than 80 end-of-chapter exercises are proposed, and the book is accompanied by a solutions manual containing the MATLAB code for computer problems; this is available

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from the publisher free of charge to those adopting this work as a textbook for courses.

ISRR, the "International Symposium on Robotics Research", is one of robotics pioneering Symposia, which has established over the past two

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coverage of the current state of robotics research.: the advances and challenges in its theoretical foundation and technology basis, and the developments in its traditional and new emerging areas of applications. The diversity, novelty, and span of the work unfolding in these areas reveal the

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field's increased maturity and expanded scope and define the state of the art of robotics and its future direction.

This elementary book provides some

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state-of-the-art research results on broad disciplinary sciences on complex networks. It presents an in-depth study with detailed description of dynamics, controls and applications of complex networks. The contents of this book can be summarized as follows. First, the dynamics of complex

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networks, for example, the cluster dynamic analysis by using kernel spectral methods, community detection algorithms in bipartite networks, epidemiological modeling with demographics and epidemic spreading on multi-layer networks, are studied. Second, the controls of

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complex networks are investigated including topics like distributed finite-time cooperative control of multi-agent systems by applying homogenous-degree and Lyapunov methods, composite finite-time containment control for disturbed second-order multi-agent systems, fractional-order

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observer design of multi-agent systems, chaos control and anticontrol of complex systems via Parrondos game and many more. Third, the applications of complex networks provide some applicable carriers, which show the importance of theories developed in complex networks. In

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particular, a general model for studying time evolution of transition networks, deflection routing in complex networks, recommender systems for social networks analysis and mining, strategy selection in networked evolutionary games, integration and methods in computational biology, are

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